

In the Abstract:

Replace the original Abstract of the Disclosure, as follows:

--A vehicle control system ~~is provided for detecting the approach of another vehicle to perform a collision avoidance action. The system comprises capturing means for capturing~~ captures an external image from the primary vehicle; ~~template memory means for storing~~ and stores templates for detecting the approach of the another vehicle in order to perform a collision avoidance action.; A template update means for updating is updated the templates when a brake pedal is pressed by a driver; ~~recognizing means for comparing~~ and the external image is compared with the template ~~and calculating an evaluation value to determine,~~ based upon the result of the comparison, whether the ~~another~~ other vehicle approaches is approaching the primary vehicle. ~~based on the result of said comparing; and instruction means for~~ The system instructing instructs the primary vehicle to perform the collision avoidance action when ~~said evaluation value~~ the comparison exceeds a threshold value. When an image similar to the template is captured and the driver does not perform a collision avoidance action such as releasing an accelerator or pressing a brake pedal, a ~~brake system~~ throttle valve is forcibly closed. ~~Thus, the~~ to inhibit accelerator ~~becomes out of control,~~ and sufficient braking force is provided even if harsh braking is performed by the driver.--